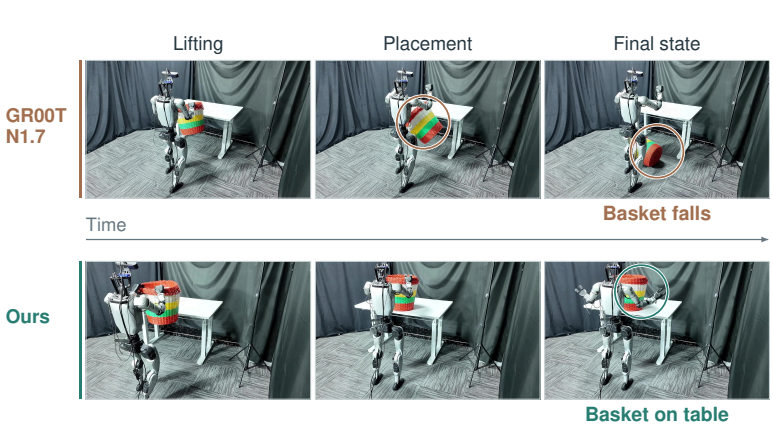
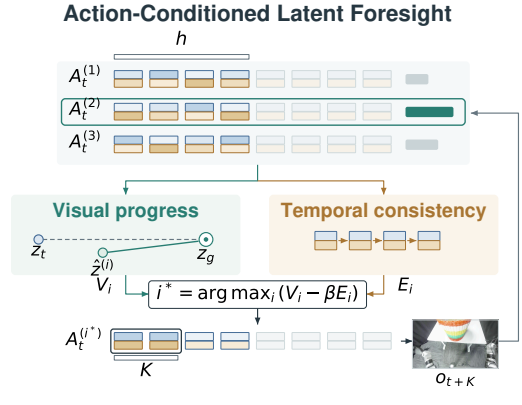

Lifting
Placement
Final state
GR00T N1.7
Basket falls
Time
Ours
Basket on table


Action-Conditioned Latent Foresight
h
$A_t^{(1)}$
$A_t^{(2)}$
$A_t^{(3)}$
Visual progress
Temporal consistency
z_t
z_g
$\hat{z}^{(i)}$
V_i
E_i
$i^* = \arg\max_i (V_i - \beta E_i)$
$A_t^{(i^*)}$
K
o_{t+K}